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Figure 1. We Use An Autonomous Agent To Implement The Adaptive Perceptual Interface. The Agent Learns A Policy For Performing A Given Task Over The Physical System, By Interacting With It. In That Process, It Acquires The State Space Of The Physical System And The Actions It Can Perform On That Space. The Agent Then Views The User As A 22th, 2024

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"Introduction To Autonomous Mobile Robots", Second Edition, MIT Press. Textbook: B. Siciliano, O. Khatib (editors), "Handbook of Robotics", 2nd Version, For "Flying Robots" chapter (co-author By Dr. Alexis) Send An E-mail Lecture Slides: Used For 9th, 2024

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2 “Uber 'not Criminally Liable' For Self-driving Death”, BBC News, 6 March 2019. 3 “Connected Automated Driving Roadmap”, ERTRAC, March 2019. 4 “Taxonomy And Definitions For Terms Related To On-Road Motor Vehicle Automated Driving S 19th, 2024

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