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Ros Control: A Generic And Simple Control Framework For ROS

Ros_control: A Generic And Simple Control Framework For ROS Sachin Chitta^{9, 11}, Eitan Marder-Eppstein¹, Wim Meeussen¹, Vijay Pradeep¹, Adolfo Rodríguez Tsouroukdissian^{12, 2}, Jonathan Bohren^{8, 10}, David Coleman^{3, 11}, Bence Magyar^{4, 2}, Gennaro Raiola^{5, 2}, Mathias Lüdtkke⁶, And Enrique Fernandez Perdomo^{7, 2} 1 HiDOF, Inc. (at The Time Of This Work) 2 PAL Robotics (at The Time Of This Work) 3 PickNik Jan 4th, 2024

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Cal Stress And Both These Phenomena Are Implicated In Sensing Mechanical Stimulation.^{28,29} Therefore, It Is Reasonable To Assume That ROS Generation And

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