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TD=0.Similarly, PID Controller Can Be Used As PI And PD Controller, By Removing Daction (Td = 0) And I-action (Tl = Maximum) Respectively. Fig 3. Step Response Of The System This Graph Is Recorded In Process History View In DeltaV Of Real Time Experimentation In Open Loop. To Find The Transfer Function Of Open Loop System Above Graph Is Used. 1th, 2024

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(8) Where Ik Is The Injected Current At Node K, Vk Is The Voltage At Node K, Ykj Is The Admittance Between Node K And J And Sk Is The Complex Power. Substituting (7) In (8), The Complex Power Can Be Written As 5th, 2024

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