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STEP 2: Stop One Motor When The Sensor On The Corresponding Side Sees The Line
STEP 3: Stop Moving The Second Motor When The Sensor On That Side Sees The Line
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Building LEGO Robots For FIRST LEGO League

About The Author And This Document Dean Hystad Is A First Class LEGO Fanatic. Dean Is An Engineer For MTS Systems Located In Eden Prairie, Minnesota. Jan 9th,

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The Brick For Possible Action According To Programmed Parameters. O Using The Same Principle As Bats And Submarines, It Uses Echo Location By Emitting An Ultrasonic Wave That Is Received Back After Bouncing Off An Object. The Time It Takes To Be Received Back Determines The Distance To That Object. Apr 1th, 2024

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