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Once The Primary Contact Points Are Located And The Relative Curvatures Are Obtained, Hertzian Theory Is Used To Predict The Size Of The Contact Zone And Consequently A Grid Of Points In The Contact Z Feb 6th, 2024

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B. Zhao, L. Zeng And Z. Wu Et Al. / Mechanism And Machine Theory 149 (2020) 103746 3 Table 1 Nomenclature. Symbol Definition I Index Of The Curvature-constraining Segments, $I = 1$ Or 2 . J Index Of The Backbones, $J = 1, 2, \dots, 8$. L_i Length Of The i th Curvature-constraining Segment L_{ci} Effective Segment Length (bent Feb 3th, 2024

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Nomenclature M Vehicle Mass, A, B Nominal Distance From Front/rear Axle To CG, L_0 , L Wheel Base Before And After Tilting, $L_0 = A + B \cos(\phi)$, H CG Height Before And After Tilting, $H = H_0 \cos(\phi)$, T W0, T Track Width Before And After Tilting, $T = T_0 / \cos(\phi)$ For Trai Jun 1th, 2024

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Omnidirectional. In Other Words, The Omnidirectional Motion Can Be Re Mar 2th, 2024

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42 G. Ni Et Al. / Mechanism And Machine Theory 113 (2017) 40-52 Fig. 2. Normal Section Of A Rack Cutter With Parabolic Modification. Fig. 3. Coordinate Relationship For Generating Beveloid Gear. Through The Coord May 6th, 2024

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