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Homework #4 Solution (Winter 2007/2008) 1. Consider The Following RRRR Manipulator (image Courtesy J. J. Craig): It Has The Following Forward Kinematics And Rotational Jacobian:  $0 \ 4T = \begin{bmatrix} 2 & 6 & 6 & 6 & 4 \\ C12c34 & -\sqrt{2} & 2s12s34 & -c12s34 & -\sqrt{2}s12c34 \\ \sqrt{2}s12c34 & \sqrt{2}s12 & \sqrt{2}c12c3 & -s12(s3 - 1) + c1 & S12c34 \\ c1 & \sqrt{2} & 2c12s34 & \dots \end{bmatrix}$  ... 7th, 2024

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